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DIPARTIMENTO DI INFORMATICA

CONCURRENT SYSTEMS

LECTURE 13

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Weak Bisimilarity

The equivalence studied up to now is quite discriminating, in the sense that it distinguishes, for example, $\tau.P$ and $\tau.\tau.P$

If an external observer can count the number of non-observable actions (i.e., the τ 's), this distinction makes sense;

If we assume that an observer cannot access any internal information of the system, then this distinction is not acceptable.

The idea of the new equivalence is to ignore (some) τ 's:

- a visible action must be replied to with the same action, possibly together with some internal actions
- an internal action must be replied to by a (possibly empty) sequence of internal actions.





$P \Longrightarrow P'$ if and only if there exist P_0, P_1, \dots, P_k
(for $k \geq 0$) such that $P = P_0 \xrightarrow{\tau} P_1 \xrightarrow{\tau} \dots \xrightarrow{\tau} P_k = P'$.

relation $\xRightarrow{\hat{\alpha}}$:

- if $\alpha = \tau$ then $\xRightarrow{\hat{\alpha}} \triangleq \Longrightarrow$;
- otherwise $\xRightarrow{\hat{\alpha}} \triangleq \Longrightarrow \xrightarrow{\alpha} \Longrightarrow$.

*S is a weak simulation if and only if $\forall (p, q) \in S \forall p \xrightarrow{\alpha} p' \exists q' \text{ s.t. } q \xRightarrow{\hat{\alpha}} q'$
and $(p', q') \in S$.*

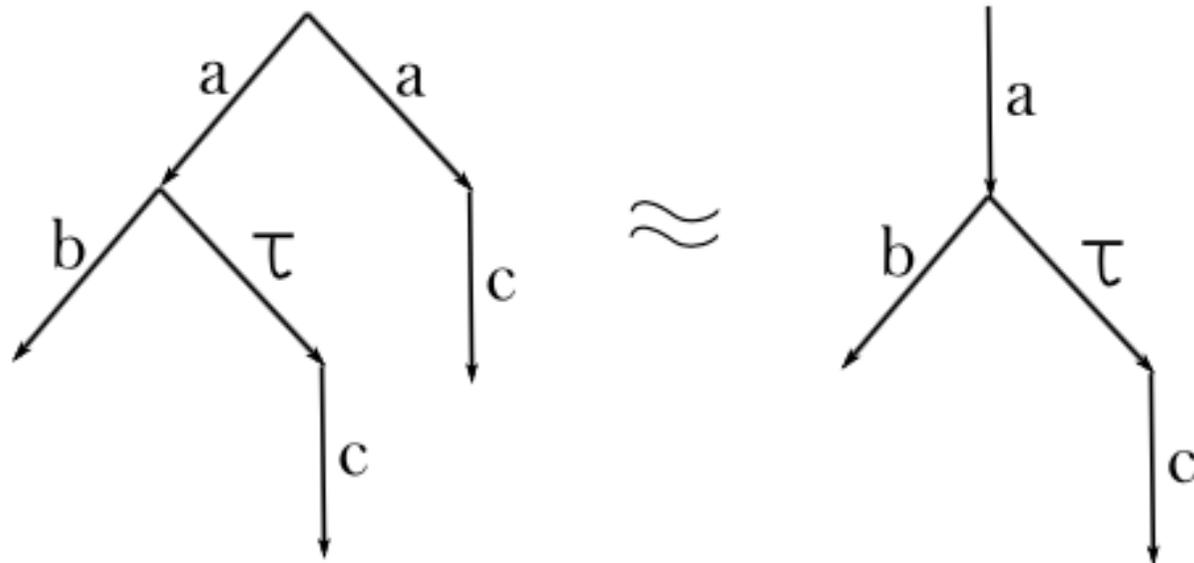
A relation S is called weak bisimulation if both S and S^{-1} are weak simulations.

We say that p and q are weakly bisimilar, written $p \approx q$, if there exists a weak bisimulation S such that $(p, q) \in S$.

Proposition

1. \approx is an equivalence.
2. \approx is a weak bisimulation.
3. \approx is a congruence.
4. $\sim \subset \approx$.

Examples of Weakly Bisimilar Proc's





Theorem 4.3. *Given any process P and any sum M, N , then:*

1. $P \approx \tau.P$;
2. $M + N + \tau.N \approx M + \tau.N$;
3. $M + \alpha.P + \alpha.(N + \tau.P) \approx M + \alpha.(N + \tau.P)$.

Proof.

take the symmetric closure of the following relations, that can be easily shown to be weak simulations:

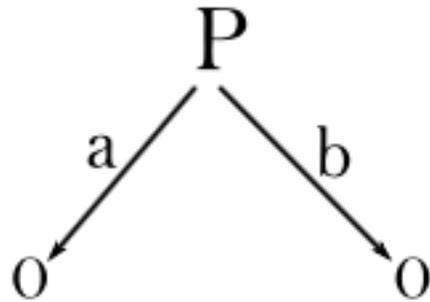
1. $S = \{(P, \tau.P)\} \cup Id$
2. $S = \{(M + N + \tau.N, M + \tau.N)\} \cup Id$
3. $S = \{(M + \alpha.P + \alpha.(N + \tau.P), M + \alpha.(N + \tau.P))\} \cup Id$

□

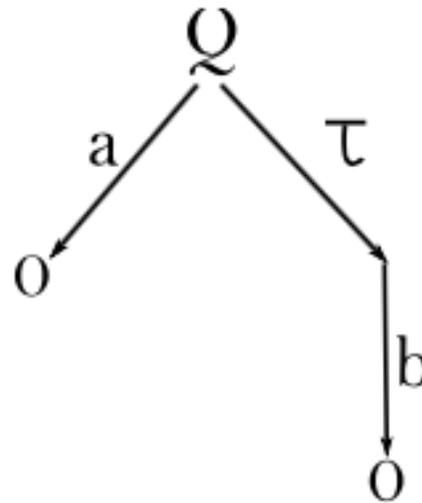




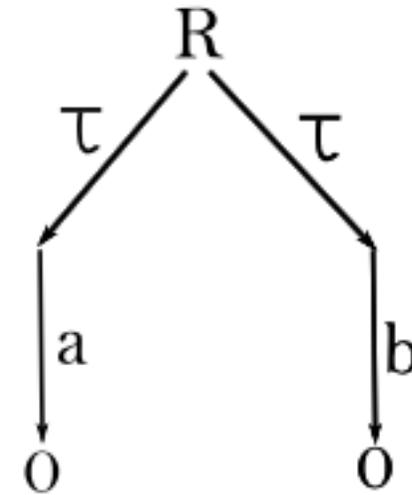
Weak Bisim abstracts from any τ ?



$$P = a + b$$



$$Q = a + \tau b$$



$$R = \tau a + \tau b$$

There exists no weak bisimulation S that contains (P, Q) .

By contr. suppose that a bisimulation exists

Since $Q \xrightarrow{\tau} b.0$, there must exist a P' such that $P \Rightarrow P'$ and $(P, b.0) \in S$

The only P' that satisfies $P \Rightarrow P'$ is P itself

hence it should be $(P, b.0) \in S$

Contradiction: P can perform a whereas $b.0$ cannot !!

Similarly, P/R and Q/R are NOT weakly bisimilar





EXAMPLE: Factory

A factory can handle three kinds of works: easy (E), medium (M) and difficult (D). An activity of the factory consists in receiving in input a work (of any kind) and in producing in output a manufactured work.

The given specification of an activity is the following:

$$\begin{aligned} A &\triangleq i_E.A' + i_M.A' + i_D.A' \\ A' &\triangleq \bar{o}.A \end{aligned}$$

where actions i_E , i_M , i_D represent they input of an easy/medium/difficult work, and \bar{o} represents the production of an output.

The factory is given by the parallel composition of two activities:

$$Factory \triangleq A|A$$





A possible implementation of this specification is obtained by having two workers that perform in parallel different kinds of work.

- For easy works, they don't use any machinery;
- For medium works, they can use either a special or a general machine;
- For difficult works, they have to use the special machine.

There is only one special and only one general machine that the workers have to share.

Hence, the specification of a worker is:

$$\begin{array}{ll} W & \triangleq i_F.W_E + i_M.W_M + i_D.W_D & S & \triangleq rs.S' \\ W_E & \triangleq \bar{o}.W & S' & \triangleq ls.S \\ W_M & \triangleq \overline{rg.lg}.W_E + \overline{rs.ls}.W_E & G & \triangleq rg.G' \\ W_D & \triangleq \overline{rs.ls}.W_E & G' & \triangleq lg.G \end{array}$$

where rg and rs are used to require the general/special machine, lg and ls are used to leave the general/special machine, and S and G implement a semaphore on the two different machines.

The resulting system is given by:

$$Workers \triangleq (W \mid W \mid G \mid S) \setminus \{rg, rs, lg, ls\}$$





We now want to show the following weak bisimilarity:

$$Factory \approx Workers$$

i.e., that the specification and the implementation of the factory behave the same (apart from internal actions)

Let N denote $\{rg,rs,lg,ls\}$ and $x,y \in \{E,M,D\}$

We can prove that the following relation is a weak bisimulation:

$$R = \{ \begin{aligned} &(A|A, (W|W \mid G|S)\backslash_N) , (A|A', (W|W_x \mid G|S)\backslash_N) , \\ &(A|A', (W|\overline{lg} \cdot W_E \mid G'|S)\backslash_N) , (A|A', (W|\overline{ls} \cdot W_E \mid G|S')\backslash_N) , \\ &(A'|A', (W_y|W_x \mid G|S)\backslash_N) , (A'|A', (W_y|\overline{lg} \cdot W_E \mid G'|S))\backslash_N , \\ &(A'|A', (W_y|\overline{ls} \cdot W_E \mid G|S'))\backslash_N , (A'|A', (\overline{lg} \cdot W_E|\overline{ls} \cdot W_E \mid G'|S'))\backslash_N \} \end{aligned}$$





The previous relation is a family of relations:

- 3 pairs of the second form (one for every x),
- 9 pairs of the fifth form (one for every x and y),
- 3 pairs of the sixth form, and
- 3 pairs of the seventh form.

Furthermore, we should also consider commutativity of parallel in pairs of the second, third, fourth, sixth, seventh and eighth form.

Thus, R is actually made up of $1+6+2+2+9+6+6+2 = 34$ pairs.





EXAMPLE: Lottery

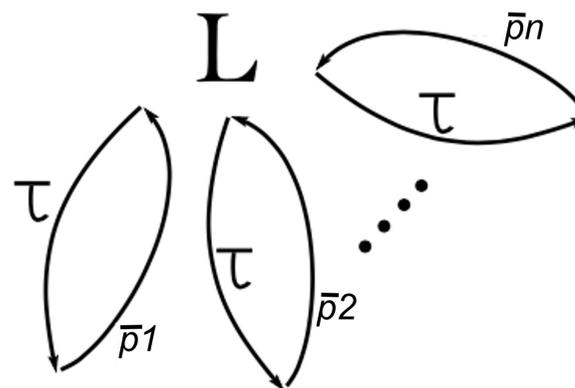
We want to model a lottery L where we can select any ball from a bag that contains n balls; after every extraction, the extracted ball is put back in the bag and the procedure is repeated.

The specification is:

$$L \triangleq \tau.\bar{p}_1.L + \tau.\bar{p}_2.L + \dots + \tau.\bar{p}_n.L$$

where τ 's represent ball extractions and \bar{p}_i is the action that communicates the value of the extracted ball.

The LTS resulting from this specification is:





We now build a system with n components, one for every ball.

Every component can be in three states:

- A (waiting for being habilitated to extraction)
- B (habilitated, with the possibility of being extracted or of habilitating the next component)
- C (extracted, waiting to externally communicate its value and start the process again):

$$A_i = a_i.B_i \quad B_i = \tau.C_i + \bar{a}_{(i \bmod n)+1}.A_i \quad C_i = \bar{p}_i.B_i$$

Actions a 's create a sort of token ring:

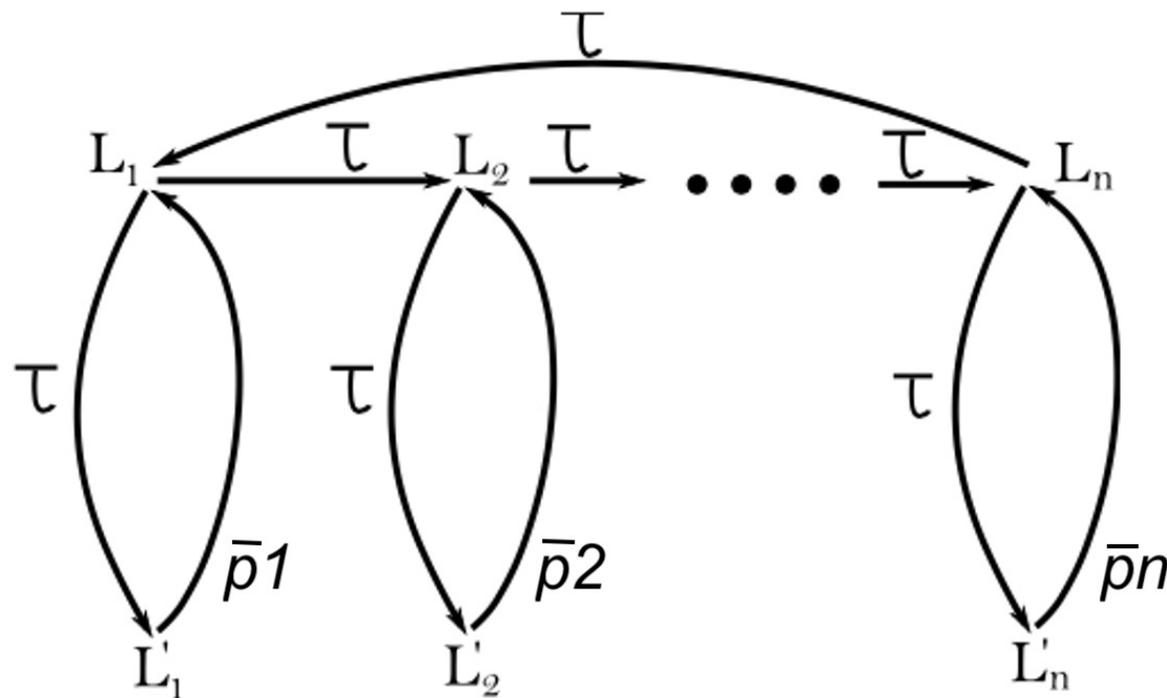
- the token is passed among the balls (only the ball with the token can be extracted)
- the ball with the token can also nondeterministically decide to pass the token to the next ball of the ring
- the token is initially given to the first ball (this choice is not mandatory: every ball can start with the token)



the system is

$$Impl \triangleq (B_1 | A_2 | \dots | A_n) \setminus \{a_1, \dots, a_n\}$$

that generates the LTS



where

$$L_i = (A_1 | \dots | A_{i-1} | B_i | A_{i+1} | \dots | A_n) \setminus \{a_1, \dots, a_n\}$$
$$L'_i = (A_1 | \dots | A_{i-1} | C_i | A_{i+1} | \dots | A_n) \setminus \{a_1, \dots, a_n\}$$





We now want to show that this system implementation is correct with respect to the given specification, i.e.

$$L \approx Impl$$

We shall prove a more general result, i.e. that, for every $i = 1, \dots, n$, we have that

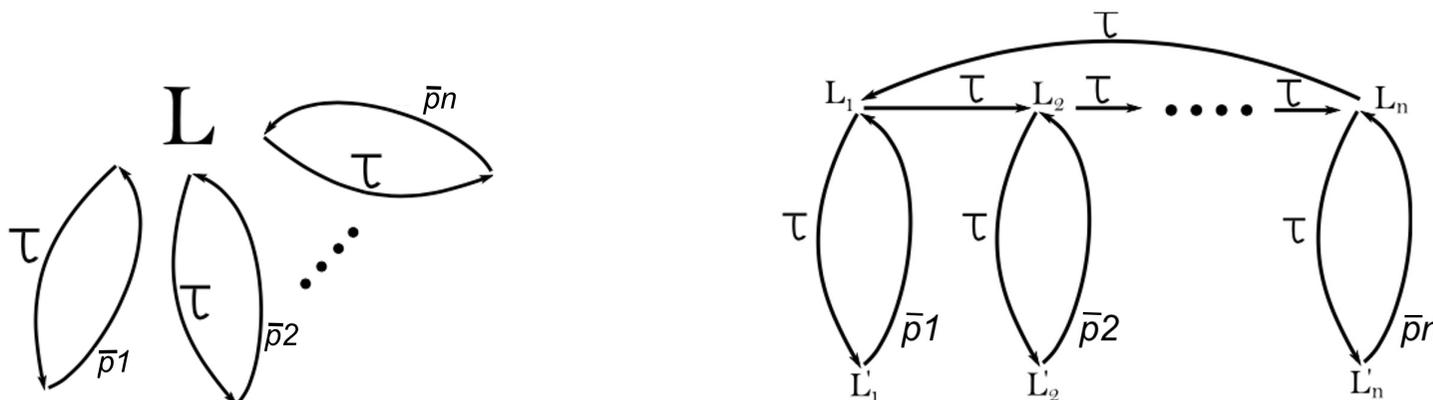
$$L \approx L_i$$

Since $Impl = L_1$, this suffices to conclude.

we prove that

$$\mathfrak{R} \triangleq \{(L, L_i) \mid 0 < i \leq n\} \cup \{(\bar{p}_i.L, L'_i) \mid 0 < i \leq n\}$$

and \mathfrak{R}^{-1} are weak simulations.



EXAMPLE: Scheduler



We have a set of processes P_i (for $0 < i \leq n$) that must repeatedly perform at certain task.

A scheduler has to guarantee that processes cyclically start their task, starting from P_1 .

Executions of different processes may overlap but the scheduler has to guarantee that every process P_i completes his performance before starting another one (with the same index i).

Every process P_i requires to start its task via action a_i and signals to the scheduler its termination via action b_i

→ the scheduler has to guarantee that the a 's cyclically occur, starting with a_1 , and, for every i , the a_i 's must alternate with the b_i 's, starting with a_i





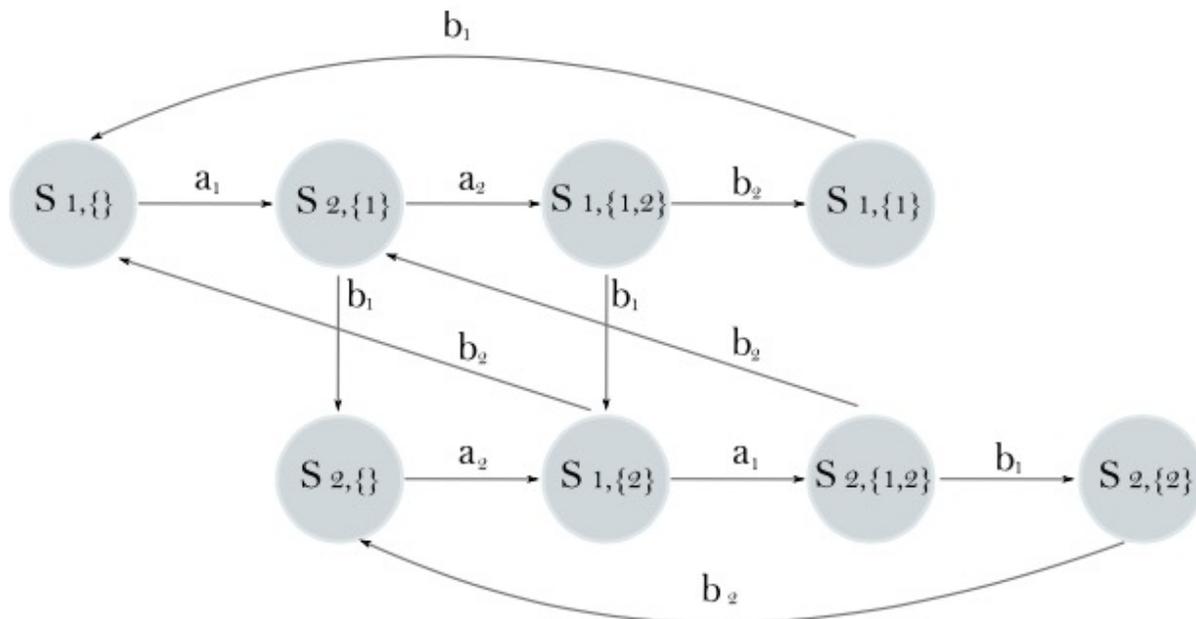
The specification of the scheduler is:

$$S_{i,X} = \begin{cases} \sum_{j \in X} b_j \cdot S_{i,X-\{j\}} & \text{if } i \in X \\ a_i \cdot S_{(i \bmod n)+1, X \cup \{i\}} + \sum_{j \in X} b_j \cdot S_{i,X-\{j\}} & \text{otherwise} \end{cases}$$

$S_{i,X}$ denotes the system waiting for activation of process P_i and where processes with indices in X are active

The starting configuration is $S_{1,\emptyset}$

The LTS for $n=2$ is:





We can try to implement the scheduler in the following way:

$$\begin{aligned}A_i &= a_i.B_i \\B_i &= \bar{c}_{(i \bmod n)+1}.C_i \\C_i &= b_i.D_i \\D_i &= c_i.A_i\end{aligned}$$

Actions of kind \bar{c} are needed to signal to the next process (i.e., with the next index) that it can start working

Actions of kind c are needed to receive from the previous process such a signal

Such actions implement a token ring; the token is initially given to the first process:

$$S = (A_1|D_2|\dots|D_n)\setminus\{c_1\dots c_n\}$$

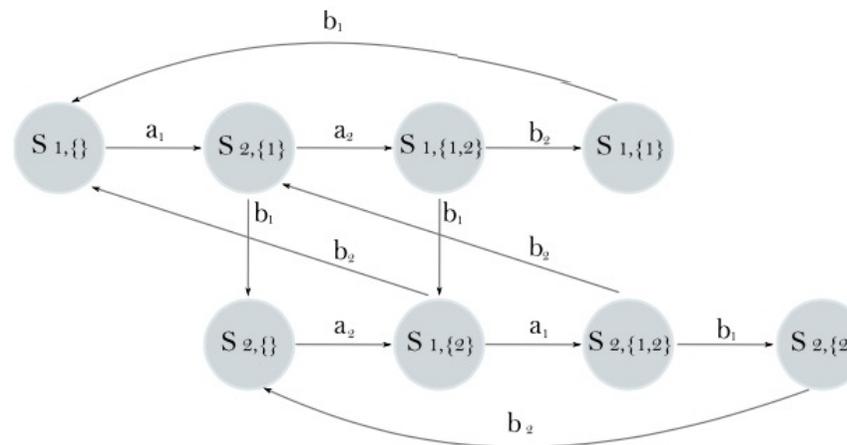
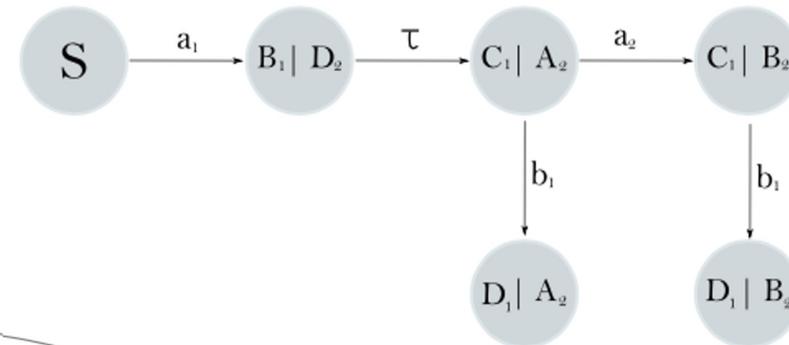
We now want to show that $S \approx S_{1,\emptyset}$





This is NOT the case. Indeed, consider the following part of the LTS for S (where in every state, names c_1 and c_2 are restricted):

$$\begin{aligned} A_i &= a_i.B_i \\ B_i &= \bar{c}_{(i \bmod n)+1}.C_i \\ C_i &= b_i.D_i \\ D_i &= c_i.A_i \end{aligned}$$



$S_{1, \{1,2\}}$ can perform b_2 whereas $(C_1 | B_2) \setminus \{c_1, c_2\}$ cannot

Problem: we have erroneously added the constraint that the i -th process cannot receive the token before its completion

→ In the implementation, action b_i always precedes action c_i

Thus, a correct implementation is: $C_i = b_i.D_i + c_i.b_i.A_i$

