

# **CONCURRENT SYSTEMS**

## **LECTURE 13**

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## Weak Bisimilarity

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The equivalence studied up to now is quite discriminating, in the sense that it distinguishes, for example,  $\tau.P$  and  $\tau.\tau.P$

If an external observer can count the number of non-observable actions (i.e., the  $\tau$ 's), this distinction makes sense;

If we assume that an observer cannot access any internal information of the system, then this distinction is not acceptable.

The idea of the new equivalence is to ignore (some)  $\tau$ 's:

- a visible action must be replied to with the same action, possibly together with some internal actions
- an internal action must be replied to by a (possibly empty) sequence of internal actions.



$P \Longrightarrow P'$  if and only if there exist  $P_0, P_1, \dots, P_k$   
(for  $k \geq 0$ ) such that  $P = P_0 \xrightarrow{\tau} P_1 \xrightarrow{\tau} \dots \xrightarrow{\tau} P_k = P'$ .

relation  $\xRightarrow{\hat{\alpha}}$  :

- if  $\alpha = \tau$  then  $\xRightarrow{\hat{\alpha}} \triangleq \Longrightarrow$ ;
- otherwise  $\xRightarrow{\hat{\alpha}} \triangleq \Longrightarrow \xrightarrow{\alpha} \Longrightarrow$ .

$S$  is a weak simulation if and only if  $\forall (p, q) \in S \ \forall p \xrightarrow{\alpha} p' \ \exists q' \text{ s.t. } q \xRightarrow{\hat{\alpha}} q' \text{ and } (p', q') \in S$ .

A relation  $S$  is called weak bisimulation if both  $S$  and  $S^{-1}$  are weak simulations.

We say that  $p$  and  $q$  are weakly bisimilar, written  $p \approx q$ , if there exists a weak bisimulation  $S$  such that  $(p, q) \in S$ .

**Proposition**

1.  $\approx$  is an equivalence.

2.  $\approx$  is a weak bisimulation.

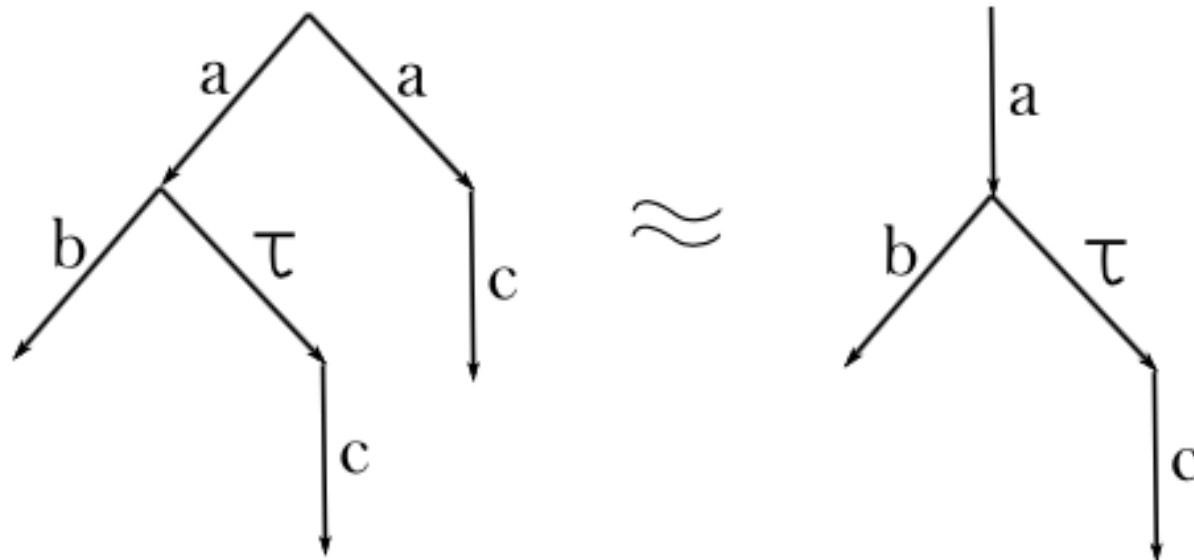
3.  $\approx$  is a congruence.

4.  $\sim \subset \approx$ .

# Examples of Weakly Bisimilar Proc's



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**Theorem 4.3.** *Given any process  $P$  and any sum  $M, N$ , then:*

1.  $P \approx \tau.P$ ;
2.  $M + N + \tau.N \approx M + \tau.N$ ;
3.  $M + \alpha.P + \alpha.(N + \tau.P) \approx M + \alpha.(N + \tau.P)$ .

*Proof.*

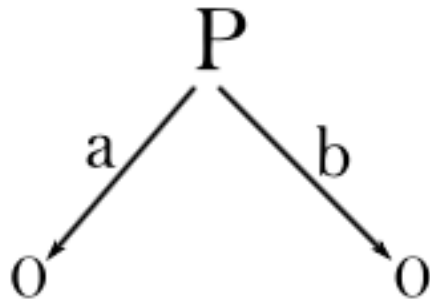
take the symmetric closure of the following relations, that can be easily shown to be weak simulations:

1.  $S = \{(P, \tau.P)\} \cup Id$
2.  $S = \{(M + N + \tau.N, M + \tau.N)\} \cup Id$
3.  $S = \{(M + \alpha.P + \alpha.(N + \tau.P), M + \alpha.(N + \tau.P))\} \cup Id$

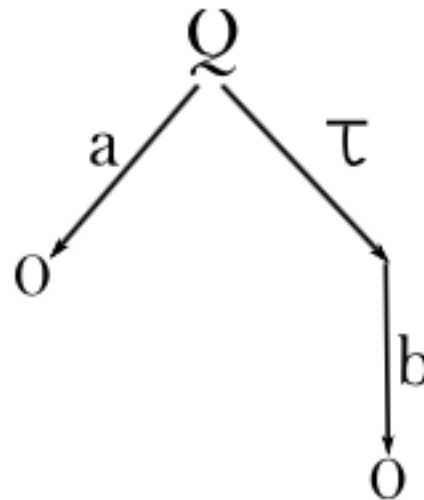
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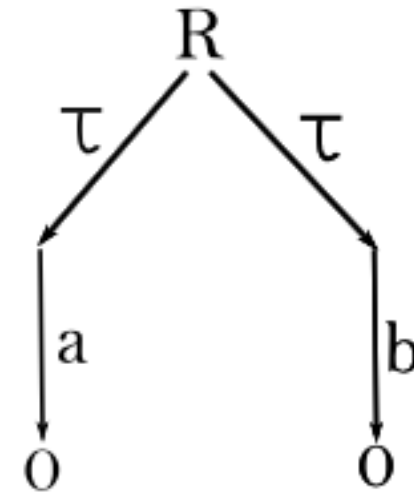
## Weak Bisim abstracts from any $\tau$ ?



$$P = a + b$$



$$Q = a + \tau b$$



$$R = \tau a + \tau b$$

There exists no weak bisimulation  $S$  that contains  $(P, Q)$ .

By contr. suppose that a bisimulation exists

Since  $Q \xrightarrow{\tau} b.0$ , there must exist a  $P'$  such that  $P \Rightarrow P'$  and  $(P, b.0) \in S$

The only  $P'$  that satisfies  $P \Rightarrow P'$  is  $P$  itself

hence it should be  $(P, b.0) \in S$

Contradiction:  $P$  can perform  $a$  whereas  $b.0$  cannot !!

Similarly,  $P/R$  and  $Q/R$  are NOT weakly bisimilar



## EXAMPLE: Factory

A factory can handle three kinds of works: easy (E), medium (M) and difficult (D). An activity of the factory consists in receiving in input a work (of any kind) and in producing in output a manufactured work.

The given specification of an activity is the following:

$$\begin{aligned} A &\triangleq i_E.A' + i_M.A' + i_D.A' \\ A' &\triangleq \bar{o}.A \end{aligned}$$

where actions  $i_E$ ,  $i_M$ ,  $i_D$  represent the input of an easy/medium/difficult work, and  $\bar{o}$  represents the production of an output.

The factory is given by the parallel composition of two activities:

$$Factory \triangleq A|A$$





A possible implementation of this specification is obtained by having two workers that perform in parallel different kinds of work.

- For easy works, they don't use any machinery;
- For medium works, they can use either a special or a general machine;
- For difficult works, they have to use the special machine.

There is only one special and only one general machine that the workers have to share.

Hence, the specification of a worker is:

$$\begin{array}{ll}
 W & \triangleq i_F.W_E + i_M.W_M + i_D.W_D & S & \triangleq rs.S' \\
 W_E & \triangleq \bar{o}.W & S' & \triangleq ls.S \\
 W_M & \triangleq \overline{rg}.lg.W_E + \overline{rs}.ls.W_E & G & \triangleq rg.G' \\
 W_D & \triangleq \overline{rs}.ls.W_E & G' & \triangleq lg.G
 \end{array}$$

where  $rg$  and  $rs$  are used to require the general/special machine,  $lg$  and  $ls$  are used to leave the general/special machine, and  $S$  and  $G$  implement a semaphore on the two different machines.

The resulting system is given by:

$$Workers \triangleq (W \mid W \mid G \mid S) \setminus \{rg, rs, lg, ls\}$$





We now want to show the following weak bisimilarity:

$$Factory \approx Workers$$

i.e., that the specification and the implementation of the factory behave the same (apart from internal actions)

Let  $N$  denote  $\{rg, rs, lg, ls\}$  and  $x, y \in \{E, M, D\}$

We can prove that the following relation is a weak bisimulation:

$$\begin{aligned} R = \{ & (A|A, (W|W \mid G|S) \setminus_N), (A|A', (W|W_x \mid G|S) \setminus_N), \\ & (A|A', (W|\overline{lg} \cdot W_E \mid G'|S) \setminus_N), (A|A', (W|\overline{ls} \cdot W_E \mid G|S') \setminus_N), \\ & (A'|A', (W_y|W_x \mid G|S) \setminus_N), (A'|A', (W_y|\overline{lg} \cdot W_E \mid G'|S)) \setminus_N, \\ & (A'|A', (W_y|\overline{ls} \cdot W_E \mid G|S')) \setminus_N, (A'|A', (\overline{lg} \cdot W_E|\overline{ls} \cdot W_E \mid G'|S')) \setminus_N \} \end{aligned}$$



The previous relation is a family of relations:

- 3 pairs of the second form (one for every x),
- 9 pairs of the fifth form (one for every x and y),
- 3 pairs of the sixth form, and
- 3 pairs of the seventh form.

Furthermore, we should also consider commutativity of parallel in pairs of the second, third, fourth, sixth, seventh and eighth form.

Thus, R is actually made up of  $1+6+2+2+9+6+6+2 = 34$  pairs.





## EXAMPLE: Lottery

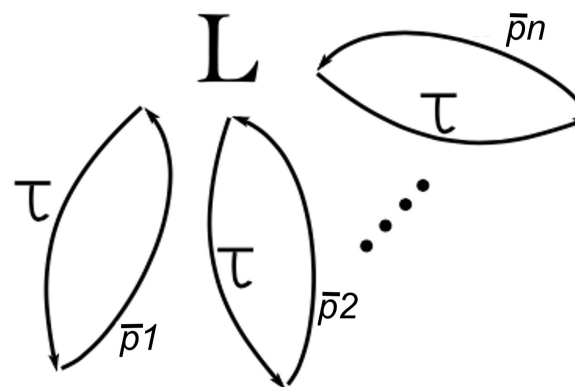
We want to model a lottery  $L$  where we can select any ball from a bag that contains  $n$  balls; after every extraction, the extracted ball is put back in the bag and the procedure is repeated.

The specification is:

$$L \triangleq \tau.\bar{p}_1.L + \tau.\bar{p}_2.L + \dots + \tau.\bar{p}_n.L$$

where  $\tau$ 's represent ball extractions and  $\bar{p}_i$  is the action that communicates the value of the extracted ball.

The LTS resulting from this specification is:





We now build a system with  $n$  components, one for every ball.

Every component can be in three states:

- A (waiting for being habilitated to extraction)
- B (habilitated, with the possibility of being extracted or of habilitating the next component)
- C (extracted, waiting to externally communicate its value and start the process again):

$$A_i = a_i.B_i \quad B_i = \tau.C_i + \bar{a}_{(i \bmod n)+1}.A_i \quad C_i = \bar{p}_i.B_i$$

Actions  $a$ 's create a sort of token ring:

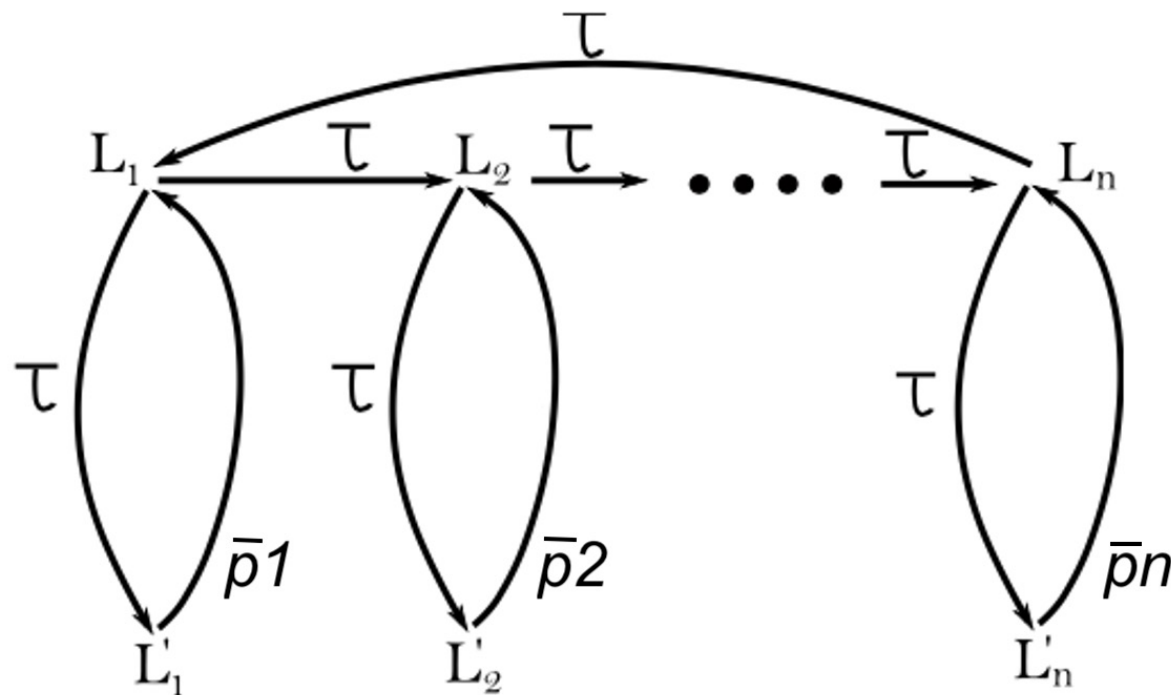
- the token is passed among the balls (only the ball with the token can be extracted)
- the ball with the token can also nondeterministically decide to pass the token to the next ball of the ring
- the token is initially given to the first ball (this choice is not mandatory: every ball can start with the token)



the system is

$$Impl \triangleq (B_1 | A_2 | \dots | A_n) \setminus \{a_1, \dots, a_n\}$$

that generates the LTS



where

$$\begin{aligned} L_i &= (A_1 | \dots | A_{i-1} | B_i | A_{i+1} | \dots | A_n) \setminus \{a_1, \dots, a_n\} \\ L'_i &= (A_1 | \dots | A_{i-1} | C_i | A_{i+1} | \dots | A_n) \setminus \{a_1, \dots, a_n\} \end{aligned}$$

We now want to show that this system implementation is correct with respect to the given specification, i.e.

$$L \approx Impl$$

We shall prove a more general result, i.e. that, for every  $i = 1, \dots, n$ , we have that

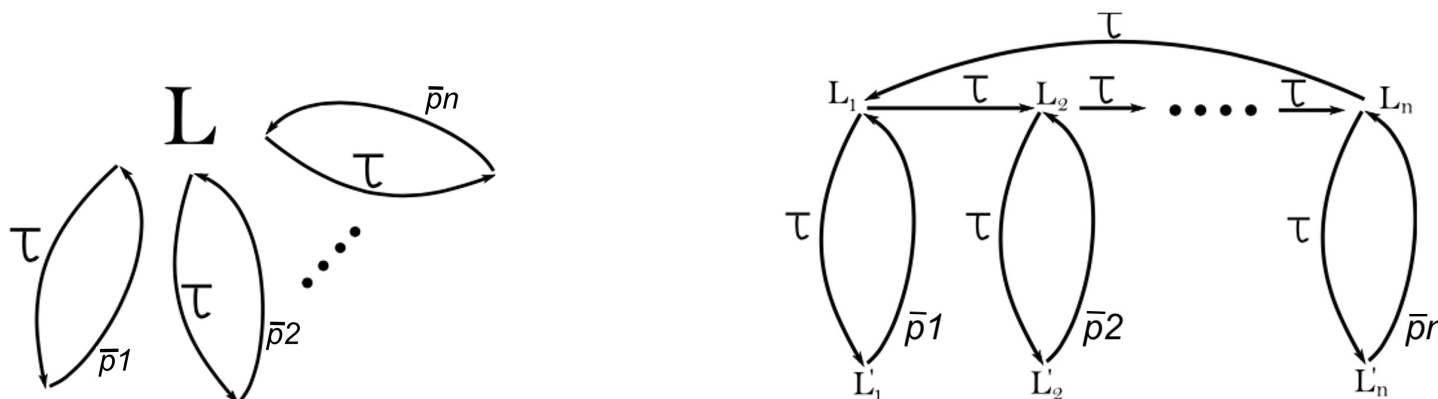
$$L \approx L_i$$

Since  $Impl = L_1$ , this suffices to conclude.

we prove that

$$\mathfrak{R} \triangleq \{(L, L_i) \mid 0 < i \leq n\} \cup \{(\bar{p}_i.L, L'_i) \mid 0 < i \leq n\}$$

and  $\mathfrak{R}^{-1}$  are weak simulations.



## EXAMPLE: Scheduler

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We have a set of processes  $P_i$  (for  $0 < i \leq n$ ) that must repeatedly perform at certain task.

A scheduler has to guarantee that processes cyclically start their task, starting from  $P_1$ .

Executions of different processes may overlap but the scheduler has to guarantee that every process  $P_i$  completes his performance before starting another one (with the same index  $i$ ).

Every process  $P_i$  requires to start its task via action  $a_i$  and signals to the scheduler its termination via action  $b_i$

→ the scheduler has to guarantee that the  $a$ 's cyclically occur, starting with  $a_1$ , and, for every  $i$ , the  $a_i$ 's must alternate with the  $b_i$ 's, starting with  $a_i$



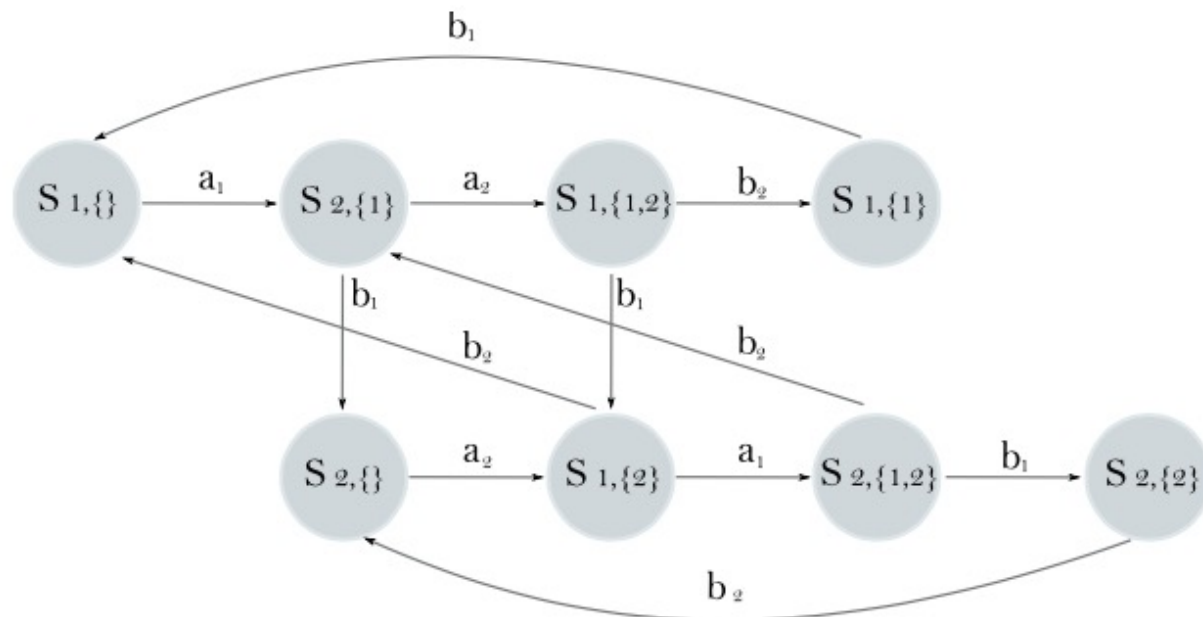
The specification of the scheduler is:

$$S_{i,X} = \begin{cases} \sum_{j \in X} b_j \cdot S_{i,X-\{j\}} & \text{if } i \in X \\ a_i \cdot S_{(i \bmod n)+1, X \cup \{i\}} + \sum_{j \in X} b_j \cdot S_{i,X-\{j\}} & \text{otherwise} \end{cases}$$

$S_{i,X}$  denotes the system waiting for activation of process  $P_i$  and where processes with indices in  $X$  are active

The starting configuration is  $S_{1,\emptyset}$

The LTS for  $n=2$  is:







We can try to implement the scheduler in the following way:

$$\begin{aligned}A_i &= a_i.B_i \\ B_i &= \bar{c}_{(i \bmod n)+1}.C_i \\ C_i &= b_i.D_i \\ D_i &= c_i.A_i\end{aligned}$$

Actions of kind  $\bar{c}$  are needed to signal to the next process (i.e., with the next index) that it can start working

Actions of kind  $c$  are needed to receive from the previous process such a signal

Such actions implement a token ring; the token is initially given to the first process:

$$S = (A_1 | D_2 | \dots | D_n) \setminus \{c_1 \dots c_n\}$$

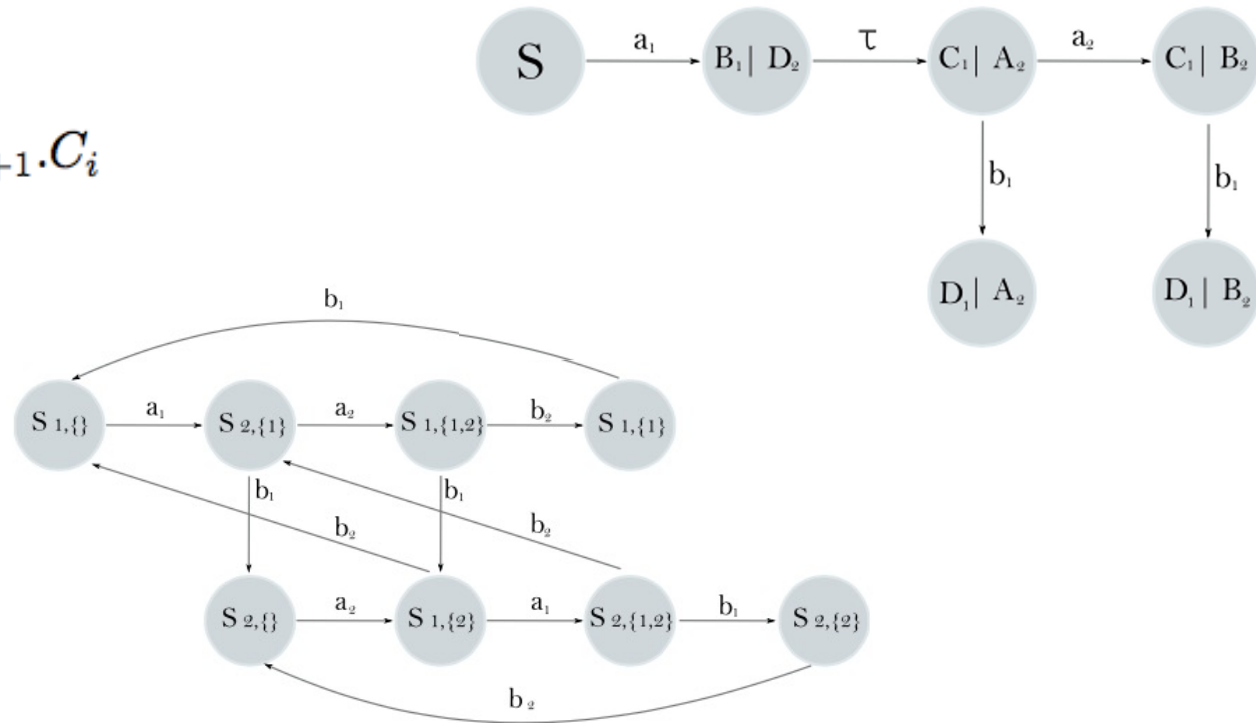
We now want to show that  $S \approx S_{1,\emptyset}$





This is NOT the case. Indeed, consider the following part of the LTS for S (where in every state, names  $c_1$  and  $c_2$  are restricted):

$$\begin{aligned} A_i &= a_i.B_i \\ B_i &= \bar{c}_{(i \bmod n)+1}.C_i \\ C_i &= b_i.D_i \\ D_i &= c_i.A_i \end{aligned}$$



$S_{1,\{1,2\}}$  can perform  $b_2$  whereas  $(C_1 | B_2) \setminus \{c_1, c_2\}$  cannot

Problem: we have erroneously added the constraint that the  $i$ -th process cannot receive the token before its completion

→ In the implementation, action  $b_i$  always precedes action  $c_i$

Thus, a correct implementation is:  $C_i = b_i.D_i + c_i.b_i.A_i$